Parallel Implementation of the Polyhedral Homotopy Method

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- PHoMpara K. Fujisawa, T. Gunji, S. Kim and M. Kojima
- Multivariate Hornor scheme M. Kojima

- 1. Polyhedral homotopy method
- 2. PHoMpara
 - Numerical results
- 3. Enumeration of all mixed cells
 - Parallel implementation
 - Dynamic enumeration ---> Takeda's Talk
- 4. Multivariate Hornor Scheme
 - Numerical results
- 5. Concluding remarks

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A system of polynomial equations f(x) = 0, where

 $\mathbb{C}=$ the set of complex numbers, $x=(x_1,x_2,\ldots,x_n)\in\mathbb{C}^n,$ $f(x)=(f_1(x),f_2(x),\ldots,f_n(x)),$ $f_j(x)=$ a polynomial in n complex variables $x_1,x_2,\ldots,x_n.$

Find all isolated solutions in \mathbb{C}^n by the polyhedral homotopy method

Rough sketch of the polyhedral homotopy method

- Based on Bernshtein's theory on bounding the number of solutions of a polynomial system in terms of its mixed volume. [Bernshtein '75]
- Currently the most powerful and practical method for computing all isolated solutions of a (large & sparse) system of polynomial equations.

Implementation on a single CPU:

- PHCpack [Verschelde]
- HOM4PS [Li and Gao]
- PHoM [Gunji, Kim, Kojima, Takeda, Fujisawa and Mizutani]
- Suitable for parallel computation;
 all isolated solutions can be computed independently in parallel.
 - PHoMpara [Gunji, Kim, Fujisawa and Kojima]
 - Verschelde and Zhuang '06

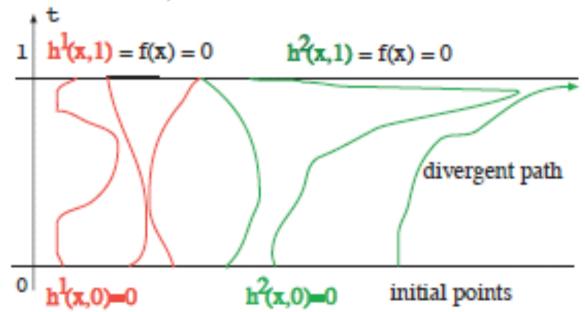
Rough sketch of the polyhedral homotopy method — 2

Phase 1. Construct a family of homotopy functions.

- \bullet Comp. of all fine mixed cells \Longrightarrow Comb. enumeration problem.
- Large scale linear program to reduce the powers of the homotopy parameter.

Phase 2. Trace homotopy paths by predictor-corrector methods.

- Highly nonlinear homotopy paths that require sophisticated techniques for step length control.
- Divergent homotopy paths. Convergence to singular solutions ("Polyhedral end game", Morgan-Sommese-Wampler '91 '92 '92, Huber-Verschelde '98).



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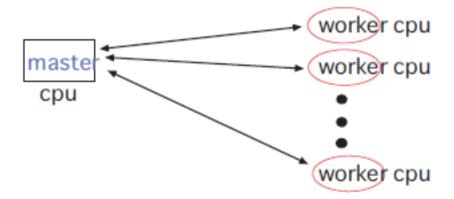
Phase 3. Verify that all isolated solutions are computed.

- The number of solutions is unknown in general.
- Approximate solutions are computed but exact solutions are never computed.

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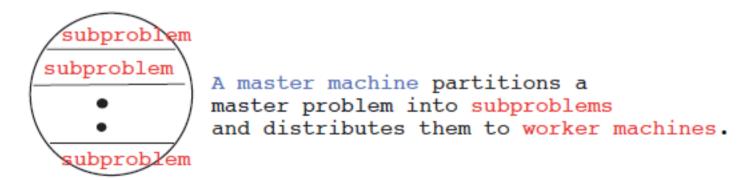
Midleware used in PHoMpara for parallel computation

• Ninf: Master-worker computing system by Sekiguchi, et al.



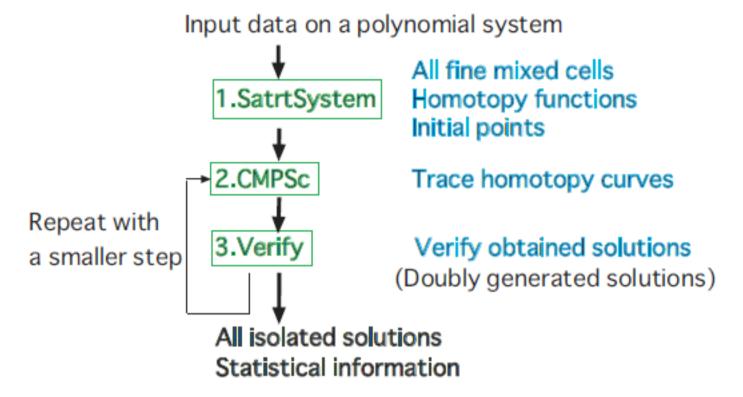
(a) Each worker can not communicate with other workers.

Master Problem



- (b) Easy to use. (c) Load balance how to partition.
- (d) Communication cost between master and worker machines.

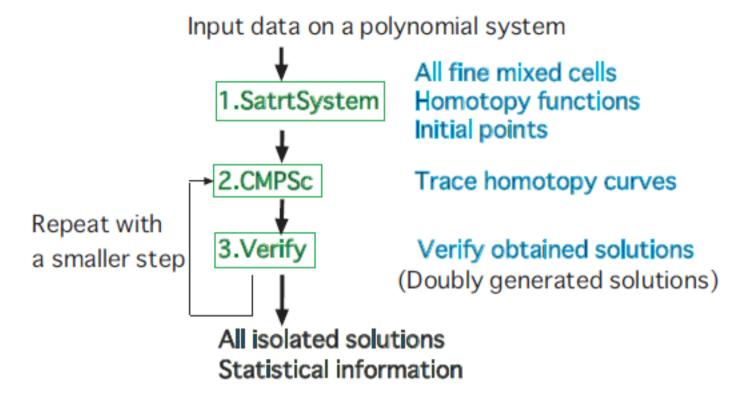
Structure of PHoMpara



Parallel computation in 1. StartSystem

- Computation of all fine mixed cells later.
- Balancing powers of the continuation parameter (Li-Verschelde 2000)
- an LP with a small # variables and a large # inequality constraints.
- a cutting plane (a column generation simplex) method.

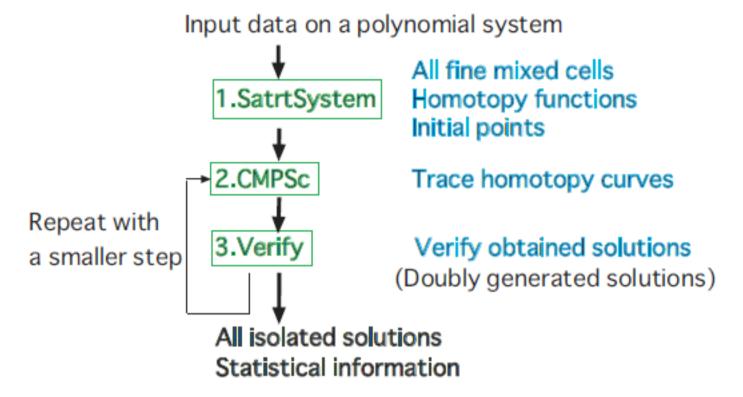
Structure of PHoMpara



Parallel computation in 2. CMPSc

- Each homotopy curve can be traced by pred.corr. method independently.
- Easy to execute in parallel; divide the h.curves to be traced into (10× #workers) sets with almost equal size, and distribute each set to each worker.

Structure of PHoMpara



Parallel computation in 3. Verify

- Let $\{x^p\}$ be generated solutions. If $\|x^q x^p\| < \epsilon$ then retrace.
- Sort $\{x^p\}$ according to their norms $\{\|x^p\|\}$ in parallel (quick sort). Then the comparison is localized;

if
$$||x^{q}|| - ||x^{p}|| > \epsilon$$
 then $||x^{q} - x^{p}|| > \epsilon$.

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 $\begin{aligned} & \text{Numerical results} - 1, \, \text{Scalability} \\ & \text{Hardware} - \text{PC cluster (AMD Athlon 2.0GHz)} \end{aligned}$

		cpu time in second			speedup
Problem	#workers	\mathbf{StSy}	CMPSc	Total	ratio
katsura-11	1	637	3,923	4,550	1.0
	10	87	395	482	9.4
	20	68	211	279	16.3
	40	58	102	160	28.4
noon-10	1	66	62,600	62,672	1.0
	10	24	6,211	6,235	10.0
	20	24	3,171	3,195	19.6
	40	27	1,770	1,797	34.9
eco-14	1	13,620	9,033	22,653	1.0
	10	1,383	909	2,292	9.9
	20	718	460	1,178	19.2
	40	388	238	626	36.2

Numerical results — 2, Large scale problems

Hardware — PC cluster (AMD Athlon 2.0GHz × 40 workers)

Problem	\mathbf{StSy}	CMPSc + Verify			Total	#sol	
		Tr.1	Tr.2	Tr.3	$\text{Tr.4}{\sim}6$		
	cpu	cpu	cpu	cpu	cpu	cpu	
		#curv	#curv	#curv	$\#\mathrm{curv}$		
eco-16	10,470	$1,\!566$	15			12,051	$16,\!384$
		16,384	8				
noon-12	78	46,737	860	871	912	49,458	531,417
		531,417	333	127	26		
katsura-15	13,638	5,224	45	57		18,964	32,768
		32,768	61	25			
RPS-10	638	256				894	1024
		1,024					
reimer-7*	9	398	399	524	2,899	4,229	2,880
		$40,\!320$	$37,\!488$	15,512	5,915		

^{*} Among 40,320 curves traced, only 2,880 converged isolated solutions. To distinguish divergent curves from convergent ones, some curves were traced 6 times — Our poor technique for detecting divergence.

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Notation

For
$$\forall a \in \mathbb{Z}_+^n \equiv \{(a_1, \dots, a_n) \geq 0 : a_j \text{ is integer}\}, \forall x \in \mathbb{C}^n, \text{ let}$$
$$x^a = x_1^{a_1} x_2^{a_2} \cdots x_n^{a_n}.$$

Write
$$\forall f_j(x)$$
 of a poly. system $f(x) = (f_1(x), \dots, f_n(x))$ as
$$f_j(x) = \sum_{a \in \mathcal{A}_j} c_j(a) x^a,$$

where $c_j(a) \in \mathbb{C}$ $(a \in \mathcal{A}_j)$ and \mathcal{A}_j a finite subset of \mathbb{Z}_+^n $(j = 1, \dots, n)$.

A family of homotopy systems in the polyhedral homotopy method.

Each polyhedral system
$$h(x,t) = (h_1(x,t), \ldots, h_n(x,t))$$
:

(3)
$$h_j(x,t) \equiv \sum_{a \in \mathcal{A}_j} c_j(a) x^a t^{\rho_j(a)} = 0, \ (x,t) \in \mathbb{C}^n \times [0,1] \ (j=1,\ldots,n)$$

$$h(x,1) \equiv f(x), h(x,0)$$
: a binomial system; $0^0 = 1$

 \uparrow each solution (α, β, ρ) induces a homotpy system

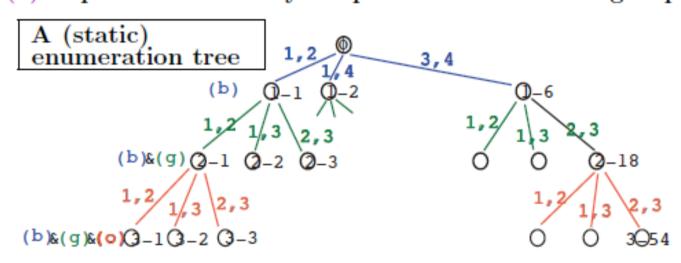
Choose $\omega_j(a) \in \mathbb{R}$ (randomly) $(a \in \mathcal{A}_j, j = 1, 2, ..., n)$. Li '99 Find all $(\alpha, \beta) \in \mathbb{R}^{2n}$ satisfying

- (1) $\rho_j(a) = \langle a, \alpha \rangle + \omega_j(a) \beta_j \geq 0 \ (a \in \mathcal{A}_j, \ j = 1, \dots, n),$ (2) for $\forall j$, exactly 2 of $\{\rho_j(a) : a \in \mathcal{A}_j\}$ are 0.

Illustration of (1) and (2): n = 3, a variable vector $(\alpha, \beta) \in \mathbb{R}^6$

(1)
$$\begin{cases} \langle a, \alpha \rangle + \omega_{1}(a) - \beta_{1} \geq 0 \ (a \in \mathcal{A}_{1} = \{a_{1}^{1}, a_{2}^{1}, a_{3}^{1}, a_{4}^{1}\}) - (b), \\ \langle a, \alpha \rangle + \omega_{2}(a) - \beta_{2} \geq 0 \ (a \in \mathcal{A}_{2} = \{a_{1}^{2}, a_{2}^{2}, a_{3}^{2}\}) - (g), \\ \langle a, \alpha \rangle + \omega_{3}(a) - \beta_{3} \geq 0 \ (a \in \mathcal{A}_{3} = \{a_{1}^{3}, a_{2}^{3}, a_{3}^{3}\}) - (o). \end{cases}$$

(2) requires that exactly 2 equalities hold in each group A_1 , A_2 , A_3 .



- A subsystem of (1), (2) is attached to each node.
- Each edge specifies two equalities in (2).

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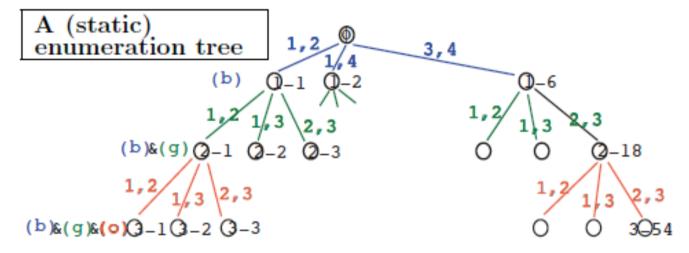
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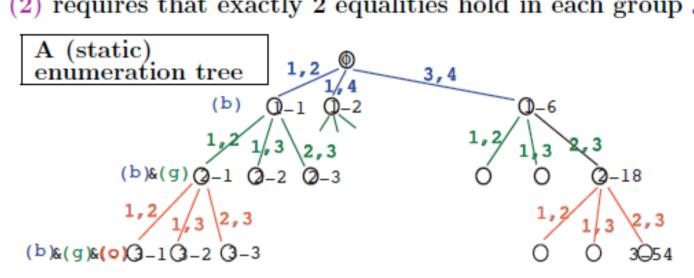


node 1-1— (b) & 2 equalities
$$\langle a, \alpha \rangle + \omega_1(a) - \beta_1 = 0$$
 $(a = a_1^1, a_2^1)$ node 2-1 — node 1-1 & (g) & $\langle a, \alpha \rangle + \omega_1(a) - \beta_1 = 0$ $(a = a_1^2, a_2^2)$ node 3-3 — nodes 1-1, 2-1 & (o) & $\langle a, \alpha \rangle + \omega_1(a) - \beta_1 = 0$ $(a = a_2^3, a_3^3)$

- a sol. (α, β) of (1) & (2) \Leftrightarrow a feasible leaf node among 3-1,..., 3-54.
- If a node ℓ -k is infeasible then so are its child nodes. \Rightarrow No sol. of (1) & (2) in the subtree with the root node ℓ -k.
- The feasibility of each node is checked by an LP simplex method.

Illustration of (1) and (2): n = 3, a variable vector $(\alpha, \beta) \in \mathbb{R}^6$

(1)
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(2) requires that exactly 2 equalities hold in each group \mathcal{A}_{1} , \mathcal{A}_{2} , \mathcal{A}_{3} .



- A single cpu implementation the depth first search to the tree. Some techniques proposed by Gao-Li-'00, Li-Li'01.
- A parallel implementation Assign a subtree to each worker; node 1-1 to worker 1, node 1-2 to worker 2, ... Additional techniques to improve the load balance among workers.

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```
a single polynomial f(x_1,\ldots,x_n).
```

a single polynomial $f(x_1, \ldots, x_n)$ & its p.derivatives.

```
a sys. of polynomials f_i(x_1, \ldots, x_n) (i = 1, \ldots, n) & their p.derivatives.
```

When n = 1, apply the Hornor scheme and the idea of Aut. Diff.

a single polynomial $f(x_1,\ldots,x_n)$.

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a sys. of polynomials $f_i(x_1,\ldots,x_n)$ $(i=1,\ldots,n)$ & their p.derivatives.

When $n \geq 2$, the situation is much more complicated.

• The Hornor scheme is not unique. Example: n=4

$$f_1(x) = c_1x_1^3 + c_2x_1^5x_2^3 + c_3x_1^4x_2^4 + c_4x_2^2 + c_5, \ f_2(x), \ f_3(x), \ f_4(x).$$

In this case, some different "Hornor factorizations" are:

$$f_1(x) = x_1^3(c_1 + c_2x_1^2x_2^3) + x_2^2(c_3x_1^4x_2^2 + c_4) + c_5 - (a), 16 \times = c_1x_1^3 + x_2^2(x_1^4x_2(c_2x_1 + c_3x_2) + c_4) + c_5 - (b), 12 \times = x_1^3(c_1 + x_1x_2^3(c_2x_1 + c_3x_2)) + c_4x_2^2 + c_5 - (c), 11 \times f_2(x), f_3(x), f_4(x) \text{ have some different Hornor factorizations too.}$$

• If monomials involved in the Hornor factorizations such as x_1^3 and $x_1^4x_2$ were evaluated independently, we could just choose "the min. Hornor factorization" for each $f_j(x)$

a single polynomial $f(x_1,\ldots,x_n)$.

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a sys. of polynomials $f_i(x_1,\ldots,x_n)$ $(i=1,\ldots,n)$ & their p.derivatives.

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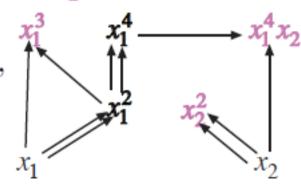
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$$f_1(x) = x_1^3(c_1 + c_2x_1^2x_2^3) + x_2^2(c_3x_1^4x_2^2 + c_4) + c_5$$
—(a), $16 \times c_1x_1^3 + x_2^2(x_1^4x_2(c_2x_1 + c_3x_2) + c_4) + c_5$ —(b), $12 \times \Rightarrow 10 \times c_1x_1^3 + x_1x_2^3(c_2x_1 + c_3x_2) + c_4x_2^2 + c_5$ —(c), $11 \times c_1x_1^3 + c_1x_2^3 + c_2x_1^3 + c_1x_2^3 + c_1x_$

 \bullet But we can save \times by evaluating all monomials together.

To compute monomials with degree ≥ 2 in (b), we need $5\times$; while $7\times$ if computed separately. Hence $f_1(x)$ can be evaluated $10\times$.



a single polynomial $f(x_1,\ldots,x_n)$.

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a sys. of polynomials $f_i(x_1,\ldots,x_n)$ $(i=1,\ldots,n)$ & their p.derivatives.

• Therefore "minimizing $\#\times$ " in evaluating ______ is a very complicated combinatorial optimization problem.

Two step methods for evaluating

- 1. A min. Hornor factorization for each $f_i(x)$, assuming that the monomials involved are computed independently next.
- 2. Efficient computation of all monomials involved in the Hornor factorizations later.

```
a single polynomial f(x_1,\ldots,x_n).
```

Here we assume that the monomials involved are computed independently.

Notation and Definition

$$(P,\alpha_p) = \sum_{p \in P} c_p x^{\alpha_p}$$
 (the coefficients $c_p \ (p \in P)$ are not relevant).

$$(Q,\alpha_p) \text{ is factorizable iff } \exists \gamma \neq 0; (Q,\alpha_p) = x^{\gamma} \left(\sum_{p \in Q} c_p x^{\alpha_p - \gamma} \right).$$

$$\mathcal{S}((P,\alpha_p)) = \{Q \subseteq P : \#Q \ge 2, \ (Q,\alpha_p) \text{ is factorizable}\}.$$

$$(P, \alpha_p) : \begin{cases} \text{non-factorizable} & \text{if } \mathcal{S}((P, \alpha_p)) = \emptyset, \\ \text{partially-factorizable} & \text{if } \mathcal{S}((P, \alpha_p)) \neq \emptyset. \end{cases}$$

 $\nu((P,\alpha_p))$: the min. $\#\times$ to evaluate (P,α_p) .

$$g(x) = 4x_1^2x_2 + 3x_1x_2^2 + 2x_2 = x_2(4x_1^2 + 3x_1^2x_2 + 2)$$
 factorizable.

In this case,

$$\nu(g(x)) = \deg(x_2) + \nu(4x_1^2 + 3x_1^2x_2 + 2).$$

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$$4x_1^2 + 2x_2^2 + 2$$
 non-factorizable.

In this case,

 $\nu(g(x)) = \text{the sum of degrees of all terms} = 2 + 2 + 0 = 4.$

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a single polynomial f(x_1,\ldots,x_n).
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$$4x_1^2 + 3x_1x_2^2 + 2x_2 = x_1(4x_1 + 3x_2^2) + 2x_2$$

= $4x_1^2 + x_2(3x_1x_2 + 2)$ partially-factorizable.

In this case,

$$\nu(g(x)) = \min\left\{ \nu(4x_1^2 + 3x_1x_2^2) + \nu(2x_2), \nu(4x_1^2) + \nu(3x_1x_2^2 + 2x_2) \right\}$$

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 is factorizable iff $\exists \gamma \neq 0; (Q, \alpha_p) = x^{\gamma} \left(\sum_{p \in Q} c_p x^{\alpha_p - \gamma} \right)$.

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 $\nu((P,\alpha_p))$: the min. $\#\times$ to evaluate (P,α_p) .

$$\nu((P,\alpha_p)) = \begin{cases} \deg(\gamma) + \nu((P,\alpha_p - \gamma)) \text{ if factorizable,} \\ \sum_{p \in P} \deg(\alpha_p) & \text{if non-factorizable,} \\ \min\{\nu((Q,\alpha_p)) + \nu((P \backslash Q,\alpha_p)) : Q \in \mathcal{S}((P,\alpha_p))\} \\ & \text{if partially-factorizable} \end{cases}$$

- The recursive formula ν + a lbd technique to compute min. $\#\times$.
- ν is too expensive for larger size poly. sys. \Rightarrow Heuristic methods.

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Numerical results: $\#\times$, where all monomials are computed independently.

	$\#\times$ (cpu time to compute $\#\times$)			
poly. system	" ν +lbd"	Heuristic	Heuristic	
(#eq, deg, #terms)	exact meth.	method1	${ m method 2}$	
game4two $(4,2,8)$	$28 \ (0.5)$	28 (0.1)	32 (0.1)	
butcher $(7,4,9)$	70 (0.7)	70 (0.2)	81 (0.2)	
pole34sys (12,3,73)	$- (\geq 3600)$	864 (3.1)	1008 (6.4)	
pltp34sys (12,4,96)	$- (\geq 3600)$	1212 (1212)	1560 (9.6)	
sparse5 $(5,10,8)$	95 (0.2)	110 (0.1)	100 (0.1)	
rose $(3,9,29)$	$- (\geq 3600)$	$63 \ (0.1)$	61 (0.1)	
cyclic-8 (8,8,8)	128 (134.7)	$150 \ (0.3)$	$128 \ (0.3)$	
cyclic-10 (10,10,10)	$- (\geq 3600)$	281 (0.6)	228 (0.6)	
cyclic-24 (24,24,24)	$- (\geq 3600)$	3443 (30.1)	1932 (11.9)	

#eq: the number of equations = the number of variables, $\deg = \max_i \deg(f_i(x)), \#$ terms = \max_i the number of terms of $f_i(x)$

" ν +lbd" exact meth. — "the recursive formula ν +lbd" technique".

H-1 — similar to Ceberio & Kreinovich 2004.

H-2 — gathering similar monomials.

Numerical results: $\#\times$, where all monomials are computed independently.

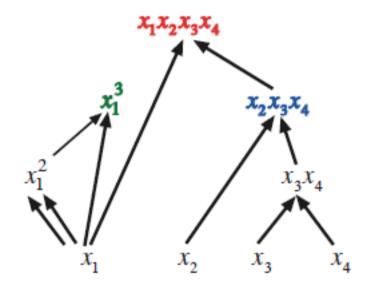
	$\#\times$ (cpu time to compute $\#\times$)			
poly. system	" ν +lbd"	Heuristic	Heuristic	
(#eq, deg, #terms)	exact meth.	method1	${ m method 2}$	
game4two $(4,2,8)$	$28 \ (0.5)$	28 (0.1)	32 (0.1)	
butcher $(7,4,9)$	70 (0.7)	70 (0.2)	81 (0.2)	
pole34sys (12,3,73)	$- (\geq 3600)$	864 (3.1)	1008 (6.4)	
pltp34sys (12,4,96)	$- (\geq 3600)$	1212 (1212)	1560 (9.6)	
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#eq: the number of equations = the number of variables, $\deg = \max_i \deg(f_i(x)), \#$ terms = \max_i the number of terms of $f_i(x)$

- " ν +lbd" is too expensive for larger deg and/or #terms cases.
- H-1 performs better in some cases, and H-2 does in some other cases.
- In practice, try some heuristic methods and choose the best one.

- 2. Efficient computation of all monomials in the Hornor factorizations.
- \Rightarrow Except $x_1, \ldots, x_n, x^{\alpha}$ is computed as the product of two lower degree monomials; $x^{\alpha} = x^{\beta}x^{\gamma}$ for some $\beta, \gamma \in \mathbb{Z}_+^n$.

Suppose monomials $x_1x_2x_3x_4$, $x_1x_2x_3$ and x_1^3 are to be computed. If we compute these monomials independently, we need $7 \times$.



In this case, $5 \times$ to compute all the monomials.

• A heuristic method for constructing this kind of graph.

- 1. Polyhedral homotopy method
- 2. PHoMpara
 - Numerical results
- 3. Enumeration of all mixed cells
 - Parallel implementation
 - Dynamic enumeration ---> Takeda's Talk
- 4. Multivariate Hornor Scheme
 - Numerical results
- 5. Concluding remarks

Our goal:

Numerically stable and fast implementation of the polyhedral homotopy method for computing all (isolated) solutions of a large scale polynomial system

Research fields

(a) Mathematical foundations on the polyhedral homotopy method

— Algebraic geometry

(b) Accurate and fast homotopy curve tracing techniques

— Numerical analysis

(c) Some techniques from optimization; LP, Implicit enumeration, etc.

Optimization

+

(d) Parallel computation

— Computer science

Our goal:

Numerically stable and fast implementation of the polyhedral homotopy method for computing all (isolated) solutions of a large scale polynomial system

Future plan for PHoM and PHoMpara

- (i) Dynamic enumeration of all mixed cells (Mizutani-Takeda-Kojima '06) into PHoM ⇒ speedup
- (ii) Methods for efficient evaluation of polynomials and their prartial derivatives (Kojima '06) into PHoM ⇒ speedup & accuracy
- (iii) "Polyhedral end games" (Huber-Verschelde '98) to detect divergence and degenerate solutions into PHoM ⇒ speedup & accuracy
- (iv) Update PHoMpara, the parallel version of PHoM taking account of
 (i), (ii) and (iii) ⇒ speedup & accuracy

Thank you!

This material is obtained at http://www.is.titech.ac.jp/~kojima/talk.html.