

Conversion Methods for Large Scale SDPs to Exploit Their Structured Sparsity

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 - Semidefinite Programs (SDPs) and their conversion —
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3. Conversion to a c-sparse LMI form **SDP with small mat. variables**
4. An application to sensor network localization
5. Concluding remarks

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Equality standard form SDP:

$$\min A_0 \bullet X \text{ sub.to } A_p \bullet X = b_p \quad (p = 1, \dots, m), \quad \mathcal{S}^n \ni X \succeq O$$

Here

$A_p \in \mathcal{S}^n$ the linear space of $n \times n$ symmetric matrices

$$\text{with the inner product } A_p \bullet X = \sum_{i, j} [A_p]_{ij} X_{ij}.$$

$b_p \in \mathbb{R}$, $X \succeq O \Leftrightarrow X \in \mathcal{S}^n$ is positive semidefinite.

Lots of Applications to Various Problems

- Systems and control theory — Linear Matrix Inequality
- SDP relaxations of combinatorial and nonconvex problems
 - Max cut and max clique problems
 - Quadratic assignment problems
 - Polynomial optimization problems
- Robust optimization
- Quantum chemistry
- Moment problems (applied probability)
- Sensor network localization problem — later
- . . .

Equality standard form SDP:

$$\min A_0 \bullet X \text{ sub.to } A_p \bullet X = b_p \quad (p = 1, \dots, m), \quad \mathcal{S}^n \ni X \succeq O$$

SDP can be large-scale easily

- $n \times n$ mat. variable X involves $n(n+1)/2$ real variables;
 $n = 2000 \Rightarrow n(n+1)/2 \approx 2$ million
- m linear equality constraints or m A_p 's $\in \mathcal{S}^n$

◇ How can we solve a larger scale SDP?

- Use more powerful computer system such as clusters and grids of computers — parallel computation.
- Develop new numerical methods for SDPs.
- Improve **primal-dual interior-point methods**.
- Convert** a large sparse SDP to **an SDP** which existing **pdipms** can solve efficiently:
 - multiple but small size mat. variables.
 - a sparse Schur complement mat. (a coef. mat. of a sys. of equations solved at \forall iteration of the **pdipm**).

An SDP example — Conversion makes a critical difference

$$\min \quad \sum_{p=1}^m x_p + \mathbf{I} \bullet \mathbf{X}$$

$$\text{sub.to} \quad a_p x_p + \mathbf{A}_p \bullet \mathbf{X} = 2, x_p \geq 0 \quad (p = 1, \dots, m), \quad \mathbf{X} \succeq \mathbf{O}.$$

Here $a_p \in (0, 1)$ and $\mathbf{A}_p \in \mathcal{S}^k$ are generated randomly.

		SeDuMi	conv.+SeDuMi
m	k	cpu time in sec.	cpu time in sec.
1000	10	29.6	4.3
2000	10	360.4	10.3
4000	10		20.9

- x_p is an LP variable which appears in a single equality constraint.
- \mathbf{X} is an SDP variable matrix which appears in all equality constraints, and its size is small.
- How can we formulate and exploit more general structured sparsity?

Outline of the conversion

structured sparsity used	a large scale and structured sparse SDP	technique
aggregated sparsity	⇓	positive definite mat. completion
	an SDP with small SDP cones and shared variables among SDP cones	
correlative sparsity	⇓ ⇓	conversion to LMI form SDP or conversion to Equality form SDP
	a c-sparse SDP with small mat. variables (i.e., small SDP cones)	

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Equality standard form SDP:

$$\min A_0 \bullet X \text{ sub.to } A_p \bullet X = b_p \ (p = 1, \dots, m), \ \mathcal{S}^n \ni X \succeq O$$

A_* : $n \times n$ aggregated sparsity pattern mat.

$$[A_*]_{ij} = \begin{cases} \star & \text{if } i = j \text{ or } [A_p]_{ij} \neq 0 \text{ for some } p = 0, \dots, m, \\ 0 & \text{otherwise} \end{cases}$$

SDP : **a-sparse** if A_* allows a sparse Cholesky factorization

Two typical cases

1: bandwidth along diagonal

$$A_* = \begin{pmatrix} \star & \star & 0 & 0 & 0 \\ \star & \star & \star & 0 & 0 \\ 0 & \star & \star & \star & 0 \\ 0 & 0 & \star & \star & \star \\ 0 & 0 & 0 & \star & \star \end{pmatrix}$$

2 : arrow ↘

$$A_* = \begin{pmatrix} \star & 0 & 0 & 0 & \star \\ 0 & \star & 0 & 0 & \star \\ 0 & 0 & \star & 0 & \star \\ 0 & 0 & 0 & \star & \star \\ \star & \star & \star & \star & \star \end{pmatrix}$$

- X : fully dense, so standard **pdipms** can not effectively utilize this type of sparsity \Rightarrow pos.def.mat.completion

Equality standard form SDP:

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SDP : **a-sparse** if A_* allows a sparse Cholesky factorization

$G(N, E)$: the **asp** graph, an undirected graph with

$$N = \{1, \dots, n\}, \ E = \{(i, j) : [A_*]_{ij} = \star \text{ and } i < j\}.$$

\Downarrow

$G(N, \bar{E})$: a chordal extension of $G(N, E)$.

$C_1, \dots, C_\ell \subset N$: the family of maximal cliques of $G(N, \bar{E})$.

SDP \equiv an SDP with shared variables among small SDP cones:

$$\min \sum_{(i,j) \in \tilde{E}} [A_0]_{ij} X_{ij}$$

$$\text{sub.to } \sum_{(i,j) \in \tilde{E}} [A_p]_{ij} X_{ij} = b_p \ (\forall p), \ \mathbf{X}(C_r) \succeq O \ (r = 1, \dots, \ell),$$

where $\mathbf{X}(C_r)$: the submatrix of \mathbf{X} consisting of X_{ij} ($i, j \in C_r$).

Here $\tilde{E} = \{(i, j) : (i, j), (j, i) \in \bar{E} \text{ or } i = j\} \implies$ **Section 3.**

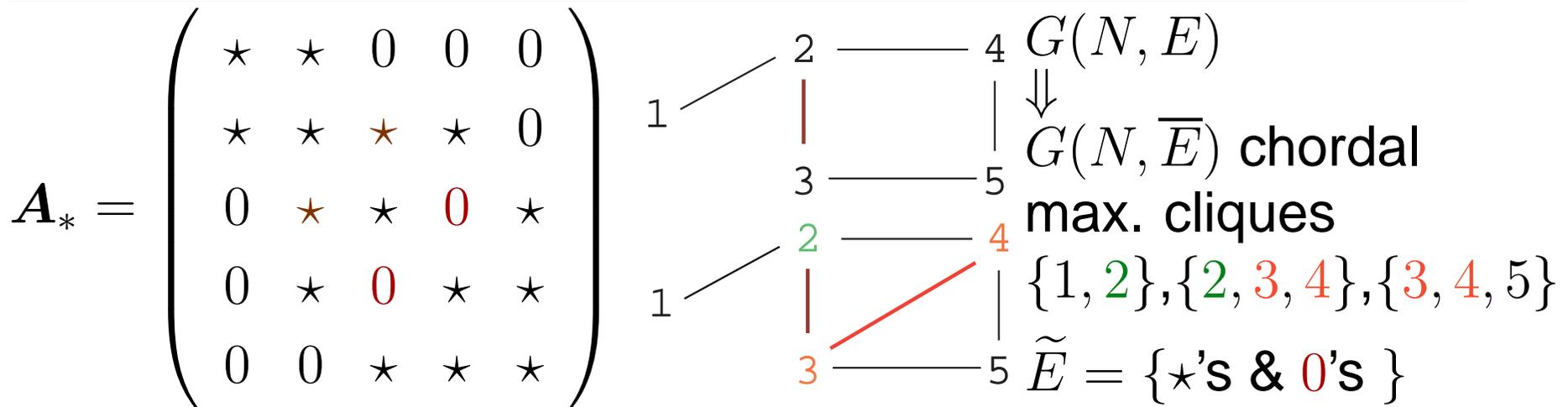
Equality standard form SDP:

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SDP : **a-sparse** if A_* allows a sparse Cholesky factorization



$$\min \sum_{(i,j) \in \tilde{E}} [A_0]_{ij} X_{ij} \text{ sub.to } \sum_{(i,j) \in \tilde{E}} [A_p]_{ij} X_{ij} = b_p,$$

$$\begin{pmatrix} X_{11} & X_{12} \\ X_{21} & X_{22} \end{pmatrix}, \begin{pmatrix} X_{22} & X_{23} & X_{24} \\ X_{32} & X_{33} & X_{34} \\ X_{42} & X_{43} & X_{44} \end{pmatrix}, \begin{pmatrix} X_{33} & X_{34} & X_{35} \\ X_{43} & X_{44} & X_{45} \\ X_{53} & X_{54} & X_{55} \end{pmatrix} \succeq O$$

Equality standard form SDP:

$$\min A_0 \bullet X \text{ sub.to } A_p \bullet X = b_p \ (p = 1, \dots, m), \ \mathcal{S}^n \ni X \succeq O$$

As an example: \Downarrow aggregated sparsity

$$\min \sum_{(i,j) \in \tilde{E}} [A_0]_{ij} X_{ij} \text{ sub.to } \sum_{(i,j) \in \tilde{E}} [A_p]_{ij} X_{ij} = b_p \text{ and}$$

$$\begin{pmatrix} X_{11} & X_{12} \\ X_{21} & X_{22} \end{pmatrix}, \begin{pmatrix} X_{22} & X_{23} & X_{24} \\ X_{32} & X_{33} & X_{34} \\ X_{42} & X_{43} & X_{44} \end{pmatrix}, \begin{pmatrix} X_{33} & X_{34} & X_{35} \\ X_{43} & X_{44} & X_{45} \\ X_{53} & X_{54} & X_{55} \end{pmatrix} \succeq O$$

(an SDP with smaller SDP cones and shared variables) \implies

Conversion into a standard form SDP to apply IPM — 2 ways

Primal form SDP with small mat. variables:

min “linear obj. in Y_{ij}^r s” sub.to “linear eq. in Y_{ij}^r s” and

$$\begin{pmatrix} Y_{11}^1 & Y_{12}^1 \\ Y_{21}^1 & Y_{22}^1 \end{pmatrix}, \begin{pmatrix} Y_{11}^2 & Y_{12}^2 & Y_{13}^2 \\ Y_{21}^2 & Y_{22}^2 & Y_{23}^2 \\ Y_{31}^2 & Y_{32}^2 & Y_{33}^2 \end{pmatrix}, \begin{pmatrix} Y_{11}^3 & Y_{12}^3 & Y_{13}^3 \\ Y_{21}^3 & Y_{22}^3 & Y_{23}^3 \\ Y_{31}^3 & Y_{32}^3 & Y_{33}^3 \end{pmatrix} \succeq O,$$

$$Y_{22}^1 = Y_{11}^2, \ Y_{22}^2 = Y_{11}^3, \ Y_{23}^2 = Y_{12}^3, \ Y_{33}^2 = Y_{22}^3.$$

Equality standard form SDP:

$$\min A_0 \bullet X \text{ sub.to } A_p \bullet X = b_p \quad (p = 1, \dots, m), \quad \mathcal{S}^n \ni X \succeq O$$

As an example: \Downarrow aggregated sparsity

$$\min \sum_{(i,j) \in \tilde{E}} [A_0]_{ij} X_{ij} \text{ sub.to } \sum_{(i,j) \in \tilde{E}} [A_p]_{ij} X_{ij} = b_p \text{ and}$$
$$\begin{pmatrix} X_{11} & X_{12} \\ X_{21} & X_{22} \end{pmatrix}, \begin{pmatrix} X_{22} & X_{23} & X_{24} \\ X_{32} & X_{33} & X_{34} \\ X_{42} & X_{43} & X_{44} \end{pmatrix}, \begin{pmatrix} X_{33} & X_{34} & X_{35} \\ X_{43} & X_{44} & X_{45} \\ X_{53} & X_{54} & X_{55} \end{pmatrix} \succeq O$$

(an SDP with smaller SDP cones and shared variables) \implies

Conversion into a standard form SDP to apply IPM — 2 ways

LMI form SDP with small mat. variables — later

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SDP with small matrix variables:

$$\begin{aligned} \min \quad & \sum_{r=1}^{\ell} \mathbf{A}_{0r} \bullet \mathbf{X}_r \\ \text{sub.to} \quad & \sum_{r=1}^{\ell} \mathbf{A}_{pr} \bullet \mathbf{X}_r = b_p \quad (p = 1, \dots, m), \quad \mathbf{X}_r \succeq \mathbf{O} \quad (\forall r) \end{aligned}$$

$$\Downarrow \quad \begin{aligned} \mathbf{A}_{p\diamond} &= \text{diag}(\mathbf{A}_{p1}, \dots, \mathbf{A}_{p\ell}), \quad \mathbf{X}_{\diamond} = \text{diag}(\mathbf{X}_1, \dots, \mathbf{X}_{\ell}), \\ \mathbf{A}_{p\diamond} \bullet \mathbf{X}_{\diamond} &= \sum_{r=1}^{\ell} \mathbf{A}_{pr} \bullet \mathbf{X}_r. \end{aligned}$$

$$\text{SDP: } \min \mathbf{A}_{0\diamond} \bullet \mathbf{X}_{\diamond} \text{ sub.to } \mathbf{A}_{p\diamond} \bullet \mathbf{X}_{\diamond} = b_p \quad (\forall p), \quad \mathbf{X}_{\diamond} \succeq \mathbf{O}$$

$m \times m$ \mathbf{R}_* : correlative sparsity pattern (csp) mat.

$$[\mathbf{R}_*]_{pq} = \begin{cases} 0 & \text{if } \mathbf{A}_{p\diamond} \text{ and } \mathbf{A}_{q\diamond} \text{ are bw-comp,} \\ \star & \text{otherwise.} \end{cases}$$

$\mathbf{A}_{p\diamond}$ and $\mathbf{A}_{q\diamond}$: block-wise complementary



$\mathbf{A}_{pr} = \mathbf{O}$ or $\mathbf{A}_{qr} = \mathbf{O}$ for every $r = 1, \dots, \ell$;

SDP with small matrix variables:

$$\begin{aligned} \min \quad & \sum_{r=1}^{\ell} \mathbf{A}_{0r} \bullet \mathbf{X}_r \\ \text{sub.to} \quad & \sum_{r=1}^{\ell} \mathbf{A}_{pr} \bullet \mathbf{X}_r = b_p \quad (p = 1, \dots, m), \quad \mathbf{X}_r \succeq \mathbf{O} \quad (\forall r) \end{aligned}$$

$$\Downarrow \quad \begin{aligned} \mathbf{A}_{p\diamond} &= \text{diag}(\mathbf{A}_{p1}, \dots, \mathbf{A}_{p\ell}), \quad \mathbf{X}_{\diamond} = \text{diag}(\mathbf{X}_1, \dots, \mathbf{X}_{\ell}), \\ \mathbf{A}_{p\diamond} \bullet \mathbf{X}_{\diamond} &= \sum_{r=1}^{\ell} \mathbf{A}_{pr} \bullet \mathbf{X}_r. \end{aligned}$$

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$$\begin{aligned} \mathbf{A}_{1\diamond} &= \text{diag}(\mathbf{A}_{11}, \mathbf{O}, \mathbf{O}, \mathbf{O}) \\ \mathbf{A}_{2\diamond} &= \text{diag}(\mathbf{O}, \mathbf{A}_{22}, \mathbf{O}, \mathbf{O}) \\ \mathbf{A}_{3\diamond} &= \text{diag}(\mathbf{O}, \mathbf{O}, \mathbf{A}_{33}, \mathbf{O}) \\ \mathbf{A}_{4\diamond} &= \text{diag}(\mathbf{A}_{41}, \mathbf{A}_{42}, \mathbf{A}_{43}, \mathbf{A}_{44}) \end{aligned} \Rightarrow \mathbf{R}_* = \begin{pmatrix} \star & 0 & 0 & \star \\ 0 & \star & 0 & \star \\ 0 & 0 & \star & \star \\ \star & \star & \star & \star \end{pmatrix}$$

\exists sparse Cholesky factorization

SDP with small matrix variables:

$$\begin{aligned} \min \quad & \sum_{r=1}^{\ell} \mathbf{A}_{0r} \bullet \mathbf{X}_r \\ \text{sub.to} \quad & \sum_{r=1}^{\ell} \mathbf{A}_{pr} \bullet \mathbf{X}_r = b_p \quad (p = 1, \dots, m), \quad \mathbf{X}_r \succeq \mathbf{O} \quad (\forall r) \end{aligned}$$

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- \mathbf{R}_* = the sparsity pattern of the Schur complement mat. = a coef. mat. of equations solved at \forall iteration of the pdipm by the Cholesky fact.

SDP : c-sparse if \mathbf{R}_* allows a sparse Cholesky factorization

c-sparse SDP with small mat. variables — target of conversion

Outline of the conversion

structured sparsity used	a large scale and structured sparse SDP	technique
aggregated sparsity	⇓	positive definite mat. completion
	an SDP with small SDP cones and shared variables among SDP cones	
correlative sparsity	⇓ ⇓	conversion to LMI form SDP or conversion to Equality form SDP
	a c-sparse SDP with small mat. variables (i.e., small SDP cones)	

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SDP with shared variables among SDP cones

$$\min \sum_{(i,j) \in \tilde{E}} [A_0]_{ij} X_{ij} \text{ sub.to } \sum_{(i,j) \in \tilde{E}} [A_p]_{ij} X_{ij} = b_p \quad (p = 1, \dots, m),$$

$$\mathbf{X}(C_r) \succeq \mathbf{O} \quad (r = 1, \dots, \ell),$$

C_1, \dots, C_r : the max. cliques of a chordal graph $G(N, \bar{E})$

$$\tilde{E} = \{(i, j) : (i, j), (j, i) \in \bar{E} \text{ or } i = j\}.$$

Represent each $\mathbf{X}(C_r)$ as

$$\mathbf{X}(C_r) = \sum_{i,j \in C_r, i \leq j} \mathbf{E}_{ij}(C_r) X_{ij},$$

where $\mathbf{E}_{ij}(C_r)$: a sym. mat. with 1 at some one or two elements and 0 elsewhere. Then, a **c-sparse LMI form SDP** having eq. const.

$$\min \sum_{(i,j) \in \tilde{E}} [A_0]_{ij} X_{ij} \text{ sub.to } \sum_{(i,j) \in \tilde{E}} [A_p]_{ij} X_{ij} = b_p \quad (\forall p),$$

$$\sum_{i,j \in C_r, i \leq j} \mathbf{E}_{ij}(C_r) X_{ij} \succeq \mathbf{O} \quad (\forall r).$$

SDP with shared variables among SDP cones

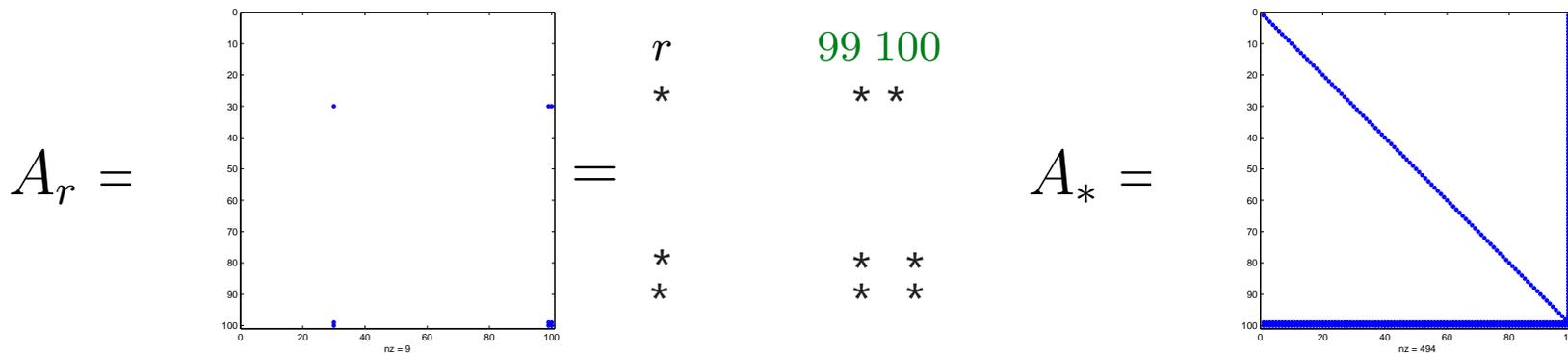
$$\min \sum_{(i,j) \in \tilde{E}} [A_0]_{ij} X_{ij} \text{ sub.to } \sum_{(i,j) \in \tilde{E}} [A_p]_{ij} X_{ij} = b_p \quad (p = 1, \dots, m),$$

$$\mathbf{X}(C_r) \succeq \mathbf{O} \quad (r = 1, \dots, \ell),$$

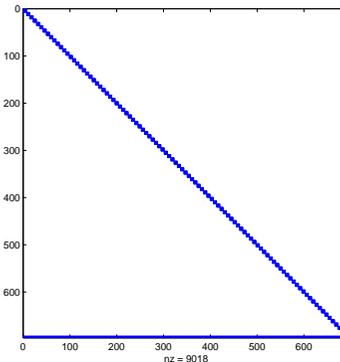
C_1, \dots, C_r : the max. cliques of a chordal graph $G(N, \bar{E})$

$$\tilde{E} = \{(i, j) : (i, j), (j, i) \in \bar{E} \text{ or } i = j\}.$$

$$n = 100, m = 98, C_r = \{r, 99, 100\} \quad (1 \leq r \leq 98).$$



R_* of LMI form SDP =



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Sensor network localization problem: Let $s = 2$ or 3 .

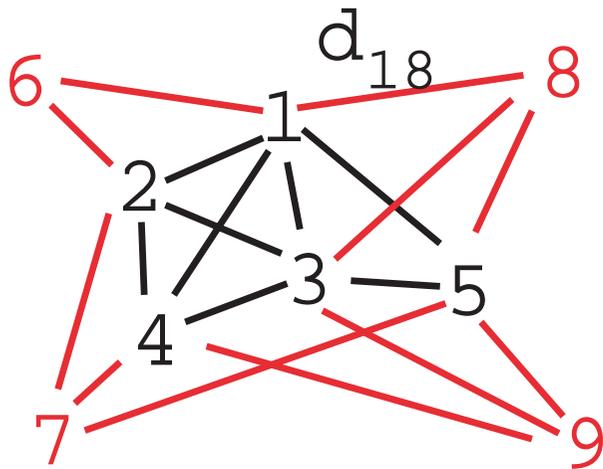
- $\mathbf{x}^p \in \mathbb{R}^s$: unknown location of sensors ($p = 1, 2, \dots, m$),
 $\mathbf{x}^r = \mathbf{a}^r \in \mathbb{R}^s$: known location of anchors ($r = m + 1, \dots, n$),
 $d_{pq} = \|\mathbf{x}^p - \mathbf{x}^q\| + \epsilon_{pq}$ — given for $(p, q) \in \mathcal{N}$,
 $\mathcal{N} = \{(p, q) : \|\mathbf{x}^p - \mathbf{x}^q\| \leq \rho = \text{a given radio range}\}$

Here ϵ_{pq} denotes a noise.

$m = 5, n = 9$.

1, ..., 5: sensors

6, 7, 8, 9: anchors



Anchors' positions are fixed.

A distance is given for \forall edge.

Compute locations of sensors.

\Rightarrow Some nonconvex QOPs

- SDP relaxation +? — **FSDP** by Biswas-Ye '06, **ESDP** by Wang et al '07, ... for $s = 2$.
- SOCP relaxation — Tseng '07 for $s = 2$.
- ...

Numerical results on 4 methods (a), (b), (c) and (d) applied to a sensor network localization problem with

m = the number of sensors dist. randomly in $[0, 1]^2$,

4 anchors located at the corner of $[0, 1]^2$,

ρ = radio distance = 0.1, no noise.

- (a) **FSDP** (b) **FSDP** + Conv. to **LMI form SDP**, as strong as (a)
- (c) **FSDP** + Conv. to **equality form SDP** as strong as (a)
- (d) **ESDP** — a further relaxation of FSDP, weaker than (a);

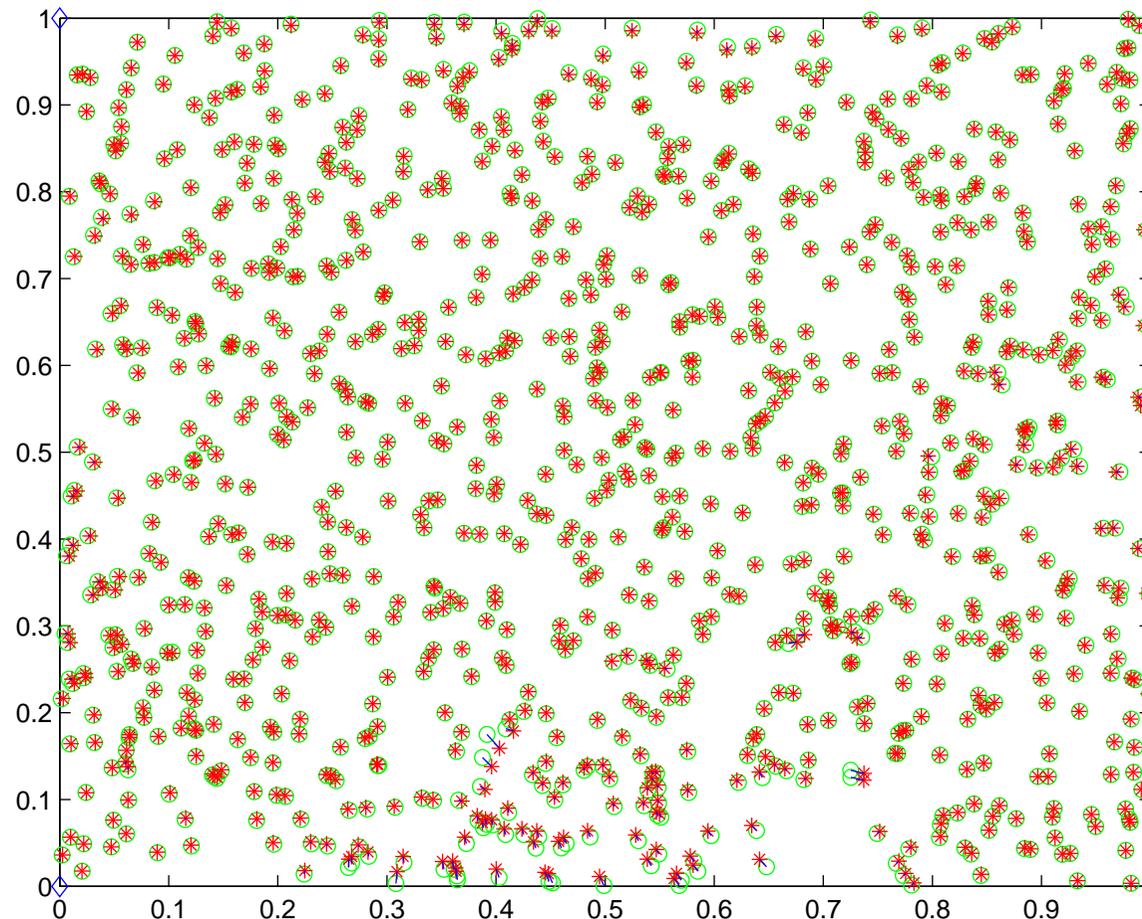
m	SeDuMi cpu time in second			
	(a)	(b)	(c)	(d)
500	389.1	35.0	69.5	62.5
1000	3345.2	60.4	178.8	200.3
2000		111.1	326.0	1403.9
4000		182.1	761.0	11559.8

SeDuMi
parameters
pars.free=0;
.eps=1.0e-5

⇒ **a-sparsity**,
c-sparsity
in (a) and (b)

A sensor network localization problem with
1000 sensors dist. randomly in $[0, 1]^2$,
4 anchors located at the corner of $[0, 1]^2$,
 $\rho =$ radio distance $= 0.1$, no noise

(b) **FSDP**+Conversion to an **LMI** form **SDP**

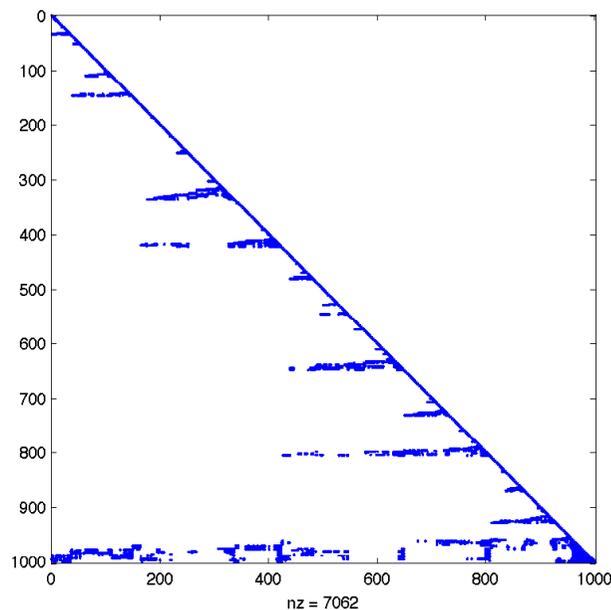


anchor : \diamond
true : \circ
computed : $*$
deviation : $—$

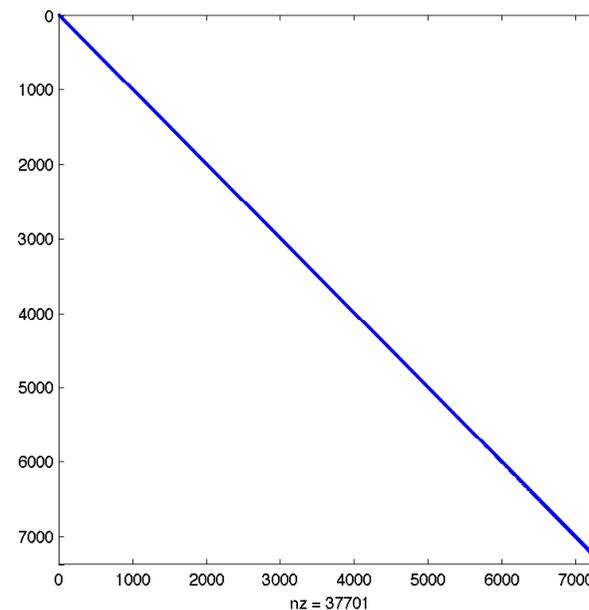
A Cholesky fact. of the **a-sparsity pattern matrix** A_* with the **symm. min. deg. ordering**

(a) **FSDP** (Biswas-Ye '06)

(b) **FSDP** + Conversion to an **LMI form SDP**



1002×1002 , $\text{nz} = 7062$
 $\text{nz density} = 0.014$

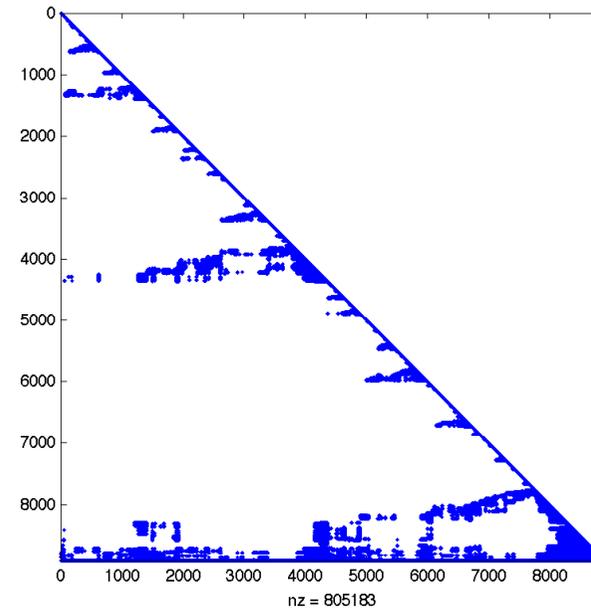
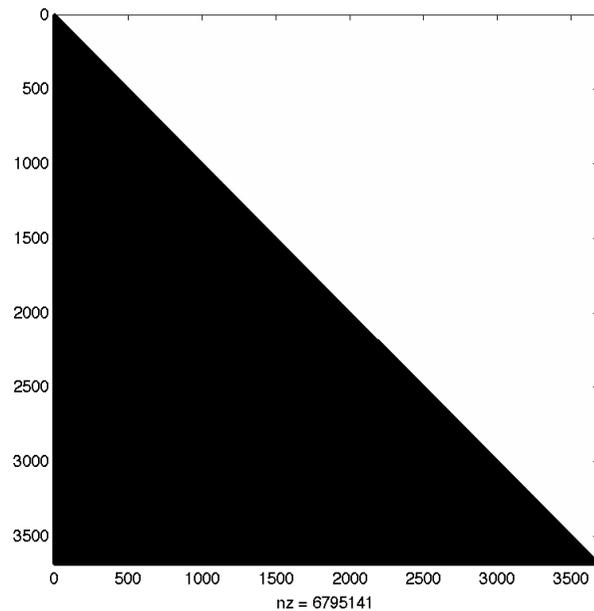


7381×7381 , $\text{nz} = 37,701$
 $\text{nz density} = 0.0014$

A Cholesky fact. of the **c-sparsity pattern matrix** R_* (= the Schur comp. matrix) with the symm. min. deg. ordering

(a) **FSDP** (Biswas-Ye '06)

(b) FSDP + Conversion to an **LMI form SDP**



3686×3686 , $\text{nz} = 6,795,141$
nz density = 1.00
3345.2 second

8916×8916 , $\text{nz} = 805,183$
nz density = 0.020
60.4 second

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2. Two kinds of sparsities
 - 2-1. Aggregated sparsity and positive definite matrix completion
 - 2-2. Correlative sparsity and sparsity of the Schur complement matrix in SDP with small mat. variables
3. Conversion to a c-sparse LMI form SDP with small mat. variables
4. An application to sensor network localization
5. **Concluding remarks**

1. Conversion of a large scale SDP into an SDP having small mat. variables and a sparse Schur complement mat. by exploiting the structured sparsity,
 - aggregated sparsity,
 - correlative sparsity.
2. Two different methods:
 - Conversion to an LMI form SDP.
 - Conversion to an equality form SDP
3. An application to sensor network localization.
⇒ S. Kim's talk on Aug. 30.

Thank you!